

1. (i) $A, B \in M_n(F)$, A 可逆: 则 $AB \sim_s BA$.

$$BA = (A^{-1}A)BA = A^{-1}(AB)A.$$

$$\Rightarrow BA \sim_c AB$$

(ii) $A, B \in SM_n(R)$, 正定.

$$A = P^t P \quad B = Q^t Q$$

$$AB = P^t P Q^t Q \quad P, Q \text{ 可逆}$$

$$\Rightarrow AB \sim_s (P^t)^{-1} P^t P Q^t Q P^t$$

" $P Q^t Q P^t = (Q P^t)^t \cdot (Q P^t)$

$\Rightarrow AB$ 相似于正定矩阵.

2. $f = t - 2 \in F[t]$ $A^2 = 2A - E$, $B = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$

$$f(A) = A^2 - 2A + E = 2A - E - 2A + E = 0$$

$$f(B) = B^2 - 2B + E = \begin{pmatrix} -1 & 2 \\ 0 & -1 \end{pmatrix}$$

$B \neq 0$, B 可逆 \Rightarrow 求 M_B , B 的极小多项式为 2.

$$B^2 + \alpha_1 B + \alpha_0 E = 0$$

$$\Rightarrow \begin{cases} \alpha_0 + \alpha_1 + 1 = 0 \\ \alpha_1 + 2 = 0 \end{cases} \Rightarrow \begin{cases} \alpha_0 = 1 \\ \alpha_1 = -2 \end{cases}$$

$$M_B = t^2 - 2t + 1.$$

$$3. \quad J_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad A = \begin{pmatrix} J_2 & 0 \\ 0 & 0 \end{pmatrix}_{4 \times 4}$$

$$B = \begin{pmatrix} J_2 & 0 \\ 0 & E_2 \end{pmatrix} \quad C = \begin{pmatrix} J_2 & 0 \\ 0 & \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix}$$

$$J_2 \text{ 不是数乘} \Rightarrow \deg \mu_{J_2} \geq 2. \quad \mu_{J_2} = t^2 \\ J^2 = 0.$$

$$\mu_A = \text{lcm}(\mu_{J_2}, \mu_0) = \text{lcm}(t^2, t) = t^2$$

$$\mu_B = \text{lcm}(\mu_{J_2}, \mu_{E_2}) = \text{lcm}(t^2, t-1) = t^2(t-1)$$

$$\mu_C = \begin{pmatrix} t^2 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\mu_M = \text{lcm}(t-2, t) = t(t-2)$$

$$\mu_C = \text{lcm}(\mu_{J_2}, \mu_M) = \text{lcm}(t^2, t(t-2)) = t^2(t-2).$$

$$4. \quad \mathcal{A}, \quad \mathcal{A}^2 = 2\mathcal{A} + 3\mathcal{E}. \quad \text{char } F \neq 2.$$

$$\text{证: } \text{rk}(\mathcal{A} + \mathcal{E}) + \text{rk}(\mathcal{A} - 3\mathcal{E}) = \dim V.$$

$$\mathcal{A}^2 - 2\mathcal{A} - 3\mathcal{E} = 0$$

$$f(t) = t^2 - 2t - 3 \\ = (t-3)(t+1)$$

$$\Rightarrow (\mathcal{A} - 3\mathcal{E})(\mathcal{A} + \mathcal{E}) = 0$$

$$\text{char } F \neq 2$$

$$\text{gcd}(t-3, t+1) = 1.$$

$$\Rightarrow \ker(\mathcal{A} - 3\mathcal{E}) \oplus \ker(\mathcal{A} + \mathcal{E}) = V$$

$$\Rightarrow n = \dim V = n - \text{rk}(\mathcal{A} - 3\mathcal{E}) + n - \text{rk}(\mathcal{A} + \mathcal{E})$$

$$\Rightarrow \text{rk}(\mathcal{A} + \mathcal{E}) + \text{rk}(\mathcal{A} - 3\mathcal{E}) = n.$$

5. (i) $\ker A^i \subset \ker A^{i+1}$

若 $v \in \ker A^i$, $A^i v = 0 \Rightarrow A^{i+1} v = A(A^i v) = A(0) = 0$

$\text{im } A^{i+1} \subset \text{im } A^i$

若 $v = A^{i+1} w \in \text{im } A^{i+1} \Rightarrow v = A^i(Aw) \in \text{im } A^i$

(ii) $\forall d_i = \dim \ker A^i$

$e_i = \dim \text{im } A^i$

且 $0 = d_0 \leq d_1 \leq \dots \leq d_i \leq \dots \leq n$

$n = e_0 \geq e_1 \geq e_2 \geq \dots \geq e_i \geq \dots \geq 0$

$\Rightarrow \exists k$ s.t. $i \geq k$ $d_i = d_k, e_i = e_k$
 i.e. $\ker A^k = \ker(A^{k+i})$ $\text{im}(A^k) = \text{im}(A^{k+i})$

(iii) $\ker(A^k) = \ker(A^{2k})$

i.e. $\text{rk}(A^k) = \text{rk}(A^{2k})$

i.e. $\text{im}(A^k) = \text{im}(A^{2k})$

核像分解 $\Rightarrow \text{im}(A^k) \oplus \ker(A^k) = V$

线性映射在商空间上诱导的映射:

A: 一般情形:

设 $A: V \longrightarrow W$ 为一线性映射.

$V_0 \subset V, W_0 \subset W$ 为子空间.

问: ① 什么时候 $\bar{A}: V/V_0 \longrightarrow W/W_0$ 是良定义?
 $\bar{v} \longmapsto \bar{Av}$

② 在哪组基下 \bar{A} 的矩阵表示良好?

$$\textcircled{1} \quad \bar{v}_1 = \bar{v}_2 \iff v_1 - v_2 \in V_0$$

$$\bar{A}(\bar{v}_1) = \bar{A}(\bar{v}_2) \iff A(v_1) - A(v_2) \in W_0 \iff A(v_1 - v_2) \in W_0 \iff v_1 - v_2 \in V_0$$

要想诱导出良定义的映射 \bar{A} , 只需 $A(V_0) \subset W_0$

$$\textcircled{2} \quad \forall v \in V_0, \Rightarrow A(v) \in W_0$$

取 (e_1, \dots, e_k) 为 V_0 的基, 扩充为 V 的基 (e_1, \dots, e_n)

$(\varepsilon_1, \dots, \varepsilon_l)$ 为 W_0 的基, 扩充为 W 的基 $(\varepsilon_1, \dots, \varepsilon_m)$

$$\text{则 } A(e_1, \dots, e_k, \dots, e_n) = (\varepsilon_1, \dots, \varepsilon_l, \dots, \varepsilon_m) \begin{pmatrix} A_1 & A_2 \\ 0 & A_3 \end{pmatrix}_{m \times n}$$

A_1 $l \times k$ 矩阵

A_2 $l \times (n-k)$ 矩阵

A_3 $(m-l) \times (n-k)$

其中 $A(e_1, \dots, e_k) = (\varepsilon_1, \dots, \varepsilon_l) \cdot A_1$

$$A(e_{k+1}, \dots, e_n) = (z_1, \dots, z_m) \begin{pmatrix} A_2 \\ A_3 \end{pmatrix}$$

$$\Rightarrow \bar{A}(\bar{e}_{k+1}, \dots, \bar{e}_n) = (\bar{z}_1, \dots, \bar{z}_m) = A_3.$$

eg: 设 $V_1, V_2 \subset V$ 为子空间.

$$A: V_1 \longrightarrow V_1 + V_2$$

$$\parallel$$

$$\text{id}$$

$$V_1 \cap V_2 \subset V_2.$$

$$\rightsquigarrow \bar{A}: \frac{V_1}{V_1 \cap V_2} \longrightarrow \frac{V_1 + V_2}{V_2}$$

取 z_1, \dots, z_s 为 $V_1 \cap V_2$ 的基,

扩充为 $e_1, \dots, e_s, f_1, \dots, f_t$ 为 V_1 的基

$e_1, \dots, e_s, g_1, \dots, g_l$ 为 V_2 的基.

$$\text{则 } A(e_1, \dots, e_s, f_1, \dots, f_t)$$

$$= (e_1, \dots, e_s, g_1, \dots, g_l, f_1, \dots, f_t)$$

$$\begin{pmatrix} E_s & | & 0 \\ \hline 0 & | & 0 \\ \hline 0 & | & E_t \end{pmatrix}$$

$\bar{f}_1, \dots, \bar{f}_t$ 为 $V_1 / V_1 \cap V_2$ 的基

同时也为 $V_1 + V_2 / V_2$ 的基

$$\Rightarrow \bar{A}(\bar{f}_1, \dots, \bar{f}_t) = (\bar{f}_1, \dots, \bar{f}_t) \cdot E + t$$

i.e. $\bar{A}: V_1/V_1 \cap V_2 \longrightarrow V_1 + V_2/V_2$ 为同构.

B: $A: V \longrightarrow V$ $V_0 \subset V$ 为子空间

$$\textcircled{1} \quad \bar{A}: V/V_0 \longrightarrow V/V_0$$

$$\bar{v} \longmapsto \bar{Av}$$

为良定义 $\Leftrightarrow A(V_0) \subset V_0 \Leftrightarrow V_0$ 为 A 子空间

$\textcircled{2}$ 取 (e_1, \dots, e_k) 为 V_0 的基, 扩充为 V 的基 (e_1, \dots, e_n)

$$\text{则 } A(e_1, \dots, e_k, \dots, e_n) = (e_1, \dots, e_k, \dots, e_n) \begin{pmatrix} A & B \\ & C \end{pmatrix}$$

$$\text{其中 } A(e_1, \dots, e_k) = (e_1, \dots, e_k) \cdot A$$

$$A(e_{k+1}, \dots, e_n) = (e_1, \dots, e_k) \cdot B + (e_{k+1}, \dots, e_n) \cdot C$$

$$\Rightarrow \bar{A}(\bar{e}_{k+1}, \dots, \bar{e}_n) = (\bar{e}_{k+1}, \dots, \bar{e}_n) \cdot C.$$

i.e. C 为 \bar{A} 在基 $\bar{e}_{k+1}, \dots, \bar{e}_n$ 下的矩阵.

二次型的化问题:

设 V 是一个向量空间, $V_0 \subset V$ 子空间

$f: V \times V \rightarrow F$ 对称双线性型.

什么时候 $\bar{f}: V/V_0 \times V/V_0 \rightarrow F$ 良定义?
 $\bar{v}_1 \quad \bar{v}_2 \longmapsto f(v_1, v_2)$

$$\bar{v}_1 = \bar{w}_1, \quad \bar{v}_2 = \bar{w}_2 \quad v_1 - w_1 \in V_0, \quad v_2 - w_2 \in V_0$$

$$\bar{f}(\bar{v}_1, \bar{v}_2) = \bar{f}(\bar{w}_1, \bar{w}_2) \Leftrightarrow f(v_1, v_2) = f(w_1, w_2)$$

$$\Leftrightarrow f(v_1, v_2) - f(w_1, v_2) + f(w_1, v_2) - f(w_1, w_2) = 0$$

$$\Leftrightarrow f(v_1 - w_1, v_2) + f(w_1, v_2 - w_2) = 0$$

要想良定义, 我们必须有 $f(v_0, v) = 0 \quad \forall v_0 \in V_0, v \in V$

i.e. 若取 e_1, \dots, e_k 为 V_0 的基, e_1, \dots, e_n 为 V 的基

f 在此基下矩阵须为 $\begin{pmatrix} 0 & 0 \\ 0 & B \end{pmatrix}$

这时 \bar{f} 在基 $\bar{e}_1, \dots, \bar{e}_n$ 下矩阵为 B .