

```

with(LinearAlgebra) :
with(QuillenSuslin) :
with(ListTools) :
with(MatrixPolynomialAlgebra) :
with(combinat) :

```

## 1.primitive decomposition algorithm

```

> gcdvector := proc (L)
    # this algo aims to compute the g.c.d. of a list of given polynomials;
    # L is a list of polynomials;
    local n, g, i;
    n := numelems(L);
    g := L[1];
    if n = 1 then
        return g;
    else
        for i from 2 to n do
            g := gcd(g, L[i]);
        end do;
        return g;
    end if;
end proc;

```

(1.1)

```

gcdvector := proc(L)
    local n, g, i;
    n := numelems(L);
    g := L[1];
    if n = 1 then
        return g
    else
        for i from 2 to n do g := gcd(g, L[i]) end do; return g
    end if
end proc

```

```

> modpx := proc (M :: Matrix, p, xvar)

    # this algo outputs a matrix whose elements mod a polynomial of a single
    variable xvar;
    # M a matrix;
    # p a polynomial of variable xvar;
    # xvar a variable;
    local m, n, i, j, A;
    m := RowDimension(M);
    n := ColumnDimension(M);
    A := Matrix(m, n);
    for i from 1 to m do
        for j from 1 to n do

```

```

        A[i, j] := rem(M[i, j], p, xvar);
    end do;
end do ;
return A;
end proc;
modpx := proc(M::Matrix, p, xvar)
    local m, n, i, j, A;
    m := LinearAlgebra:-RowDimension(M);
    n := LinearAlgebra:-ColumnDimension(M);
    A := Matrix(m, n);
    for i to m do for j to n do A[i, j] := rem(M[i, j], p, xvar) end do end do;
    return A
end proc

```

(1.2)

```

> factorirrfactors := proc(p)
    # factor a polynomial into irreducible parts;
    # p a polynomial;
    local L, LL, l, s, i, j;
    L := factors(p);
    l := numelems(L[2]);
    LL := [ ];
    for i from 1 to l do
        s := L[2][i][2];
        for j from 1 to s do
            LL := [op(LL), L[2][i][1]];
        end do;
    end do;
    return LL;
end proc;
factorirrfactors := proc(p)
    local L, LL, l, s, i, j;
    L := factors(p);
    l := numelems(L[2]);
    LL := [ ];
    for i to l do
        s := L[2][i][2]; for j to s do LL := [op(LL), L[2][i][1]] end do
    end do;
    return LL
end proc

```

(1.3)

```

> diagdenomcol := proc(M)
    # extract the lcm of each column elements' denom;
    # M a matrix;
    local n, m, den, i, j, ll;
    m := RowDimension(M);

```

```

    n := ColumnDimension(M);
    den := [ ];
    for i from 1 to n do
        ll := denom(M[1, i]);
        for j from 1 to m do
            ll := lcm(ll, denom(M[j, i]));
        end do;
        den := [op(den), ll];
    end do;
    return DiagonalMatrix(den);
end proc;
diagdenomcol := proc(M)
    local n, m, den, i, j, ll;
    m := LinearAlgebra:-RowDimension(M);
    n := LinearAlgebra:-ColumnDimension(M);
    den := [ ];
    for i to n do
        ll := denom(M[1, i]);
        for j to m do ll := lcm(ll, denom(M[j, i])) end do;
        den := [op(den), ll]
    end do;
    return LinearAlgebra:-DiagonalMatrix(den)
end proc
=
> checkzerorow := proc(M::Matrix, row)

    # Check if a matrix has zero rows, 'row' returns the corresponding row
    # number if there are zero row with extries all 0
    local m, n, i, j;
    m := RowDimension(M);
    n := ColumnDimension(M);
    for i from row to m do
        j := 1;
        while M[i, j] = 0 do
            if j < n then
                j := j + 1;
            else
                return i;
            end if ;
        end do;
    end do;
    return 0;
end proc;
checkzerorow := proc(M::Matrix, row)
    local m, n, i, j;

```

(1.4)

(1.5)

```

m := LinearAlgebra:-RowDimension(M);
n := LinearAlgebra:-ColumnDimension(M);
for i from row to m do
    j := 1;
    while M[i, j] = 0 do
        if j < n then j := j + 1 else return i end if
    end do
end do;
return 0

```

end proc

```

> checkzerorowfromrc := proc(M::Matrix, row, r, c)
    # Starting from the r'th row and c'th column of matrix M, check whether the
    # submatrix at the lower right corner of M has a zero row, 'row' returns the
    # corresponding row number when there is a row in which all elements are 0
    local m, n, i, j;
    m := RowDimension(M);
    n := ColumnDimension(M);
    for i from r to m do
        j := c;
        while M[i, j] = 0 do
            if j < n then
                j := j + 1;
            else
                row := i;
                return true;
            end if ;
        end do;
    end do;
    return false;
end proc;

```

checkzerorowfromrc := proc(M::Matrix, row, r, c)

(1.6)

```

    local m, n, i, j;
    m := LinearAlgebra:-RowDimension(M);
    n := LinearAlgebra:-ColumnDimension(M);
    for i from r to m do
        j := c;
        while M[i, j] = 0 do
            if j < n then j := j + 1 else row := i; return true end if
        end do
    end do;
    return false

```

end proc

```

> findcolumn :=proc(M, r, c)
  # Starting from the r'th row and c'th column of matrix M, check whether the
  submatrix at the lower right corner of M has a column which has nonzero
  element, if exists, return the corresponding column number.
  local m, n, i, j;
  m := RowDimension(M);
  n := ColumnDimension(M);
  for j from c to n do
    for i from r to m do
      if M[i, j]  $\neq$  0 then
        return j;
      end if;
    end do;
  end do;
  return false;
end proc;
findcolumn := proc(M, r, c)

```

(1.7)

```

  local m, n, i, j;
  m := LinearAlgebra:-RowDimension(M);
  n := LinearAlgebra:-ColumnDimension(M);
  for j from c to n do
    for i from r to m do
      if M[i, j]<>0 then return j end if
    end do
  end do;
  return false
end proc

```

```

> degree00 :=proc(f, vv)

```

```

  # return the degree of a poly f with respect to the variable vv, return +
   $\infty$  if the degree is less than 0.

```

```

  local d;
  d := degree(f, vv);
  if d < 0 then
    d := +  $\infty$ ;
  end if;
  return d;
end proc;

```

```

degree00 := proc(f, vv)

```

(1.8)

```

  local d;
  d := degree(f, vv); if d < 0 then d := infinity end if; return d
end proc

```

```

> interchangerow :=proc(L, R, Rmod, r, j0, yvar)

```

*# The input matrix  $L$  and  $R$  are required to make  $M = LR$ . The returned  $M'$  is the result of swapping some rows of the matrix  $M$  so that the element position at the  $j0$ th column and  $r$ th row of  $M$  has the smallest degree in the current column.*

```

local m, n, LL, i, k, mini, D;
m := RowDimension(R);
n := ColumnDimension(R);
LL := [ ];
k := m - r + 1;
for i from r to m do
    LL := [op(LL), degree00(Rmod[i, j0], yvar)];
end do;
mini := LL[1];
for i from 1 to k do
    if LL[i] < mini then
        mini := LL[i];
    end if;
end do;
i := Search(mini, LL);
D := RowOperation(IdentityMatrix(m), [r, r + i - 1]);
return L • D, D-1 • R;

```

**end proc**;

*interchangerow := proc(L, R, Rmod, r, j0, yvar)*

(1.9)

```

local m, n, LL, i, k, mini, D;
m := LinearAlgebra:-RowDimension(R);
n := LinearAlgebra:-ColumnDimension(R);
LL := [ ];
k := m - r + 1;
for i from r to m do LL := [op(LL), degree00(Rmod[i, j0], yvar)] end do;
mini := LL[1];
for i to k do if LL[i] < mini then mini := LL[i] end if end do;
i := ListTools:-Search(mini, LL);
D := LinearAlgebra:-RowOperation(LinearAlgebra:-IdentityMatrix(m), [r, r
+ i - 1]);
return Typesetting:-delayDotProduct(L, D), Typesetting:-delayDotProduct(1
/D, R)

```

**end proc**

**> euclidcolumnreduce := proc(L, R, Rmod, r, c, p, xvar, yvar)**

*# Perform column Gauss reduction on the matrix and return L, R such that  $M = LR$*

```

local m, n, i, k, al, bl, bb, ss, tt, aa, ql, rl, qq, rr, E, DD;

```

```

    m := RowDimension(R);
    n := ColumnDimension(R);
    al := [ ];
    k := m - r + 1;
    for i from r to m do
        al := [op(al), Rmod[i, c]];
    end do;
    bb := lcoeff(al[1], yvar);
    gcdex(bb, p, xvar, 'ss', 'tt');
    aa := ss*al[1];
    aa := rem(aa, p, xvar);
    ql := [ ];
    rl := [ ];
    for i from 2 to k do
        rr := rem(al[i], aa, yvar, 'qq');
        rl := [op(rl), rr];
        ql := [op(ql), qq];
    end do;
    E := IdentityMatrix(k);
    for i from 2 to k do
        E := RowOperation(E, [i, 1], -ss*ql[i-1]) ;
    end do;
    DD := DiagonalMatrix([ IdentityMatrix(r-1), E]);
    return L • DD-1, DD • R;
end proc;
euclidcolumnreduce := proc(L, R, Rmod, r, c, p, xvar, yvar)
    local m, n, i, k, al, bl, bb, ss, tt, aa, ql, rl, qq, rr, E, DD;
    m := LinearAlgebra:-RowDimension(R);
    n := LinearAlgebra:-ColumnDimension(R);
    al := [ ];
    k := m - r + 1;
    for i from r to m do al := [op(al), Rmod[i, c]] end do;
    bb := lcoeff(al[1], yvar);
    gcdex(bb, p, xvar, 'ss', 'tt');
    aa := ss*al[1];
    aa := rem(aa, p, xvar);
    ql := [ ];
    rl := [ ];
    for i from 2 to k do
        rr := rem(al[i], aa, yvar, 'qq'); rl := [op(rl), rr]; ql := [op(ql),
        qq]
    end do;
    E := LinearAlgebra:-IdentityMatrix(k);

```

(1.10)

```

for i from 2 to k do
  E := LinearAlgebra:-RowOperation(E, [i, 1], -ss*ql[i - 1])
end do;
DD := LinearAlgebra:-DiagonalMatrix([LinearAlgebra:-
IdentityMatrix(r - 1), E]);
return Typesetting:-delayDotProduct(L, 1/DD), Typesetting:-
delayDotProduct(DD, R)

```

end proc

---

```

> judgezeroele := proc(R, r, c)

```

*#Determine whether there is a non-zero element in the cth column of matrix R from the rth row to the end of this column. If there is a non-zero element, return 0, otherwise return 1*

```

  local i, m;
  m := RowDimension(R);
  for i from r+1 to m do
    if R[i, c] ≠ 0 then
      return 0;
    end if;
  end do;
  return 1;

```

end proc;

```

judgezeroele := proc(R, r, c)

```

(1.11)

```

  local i, m;
  m := LinearAlgebra:-RowDimension(R);
  for i from r+1 to m do if R[i, c] <> 0 then return 0 end if end do;
  return 1

```

end proc

---

```

> factorsingleirrfactor := proc(L, R, p, xvar, yvar)

```

*#The procedure for performing a primitive decomposition of the matrix M with respect to a single irreducible polynomial*

```

  local m, n, i0, j0, LL, RR, Rmod, r1, D0;
  m := RowDimension(R);
  n := ColumnDimension(R);
  i0 := 1;
  j0 := 1;
  LL := L;
  RR := R;
  Rmod := modpx(RR, p, xvar);
  r1 := checkzerorow(Rmod, i0);

```



```

D0 := IdentityMatrix(m);
while r1 = 0 do
  j0 := findcolumn(Rmod, i0, j0);
  while judgezeroele(Rmod, i0, j0) = 0 do
    LL, RR := interchangerow(LL, RR, Rmod, i0, j0, yvar);
    Rmod := modpx(RR, p, xvar);
    LL, RR := euclidcolumnreduce(LL, RR, Rmod, i0, j0, p, xvar, yvar);
    Rmod := modpx(RR, p, xvar);
  end do;
  i0 := i0 + 1;
  j0 := j0 + 1;
  r1 := checkzerorow(Rmod, i0);
end do;
D0 := RowOperation(D0, r1, p);
RR := D0-1 • RR;
return simplify(LL • D0), simplify(RR);
end proc;

```

(1.12)

```

factorsingleirrfactor := proc(L, R, p, xvar, yvar)
  local m, n, i0, j0, LL, RR, Rmod, r1, D0;
  m := LinearAlgebra:-RowDimension(R);
  n := LinearAlgebra:-ColumnDimension(R);
  i0 := 1;
  j0 := 1;
  LL := L;
  RR := R;
  Rmod := modpx(RR, p, xvar);
  r1 := checkzerorow(Rmod, i0);
  D0 := LinearAlgebra:-IdentityMatrix(m);
  while r1 = 0 do
    j0 := findcolumn(Rmod, i0, j0);
    while judgezeroele(Rmod, i0, j0) = 0 do
      LL, RR := interchangerow(LL, RR, Rmod, i0, j0, yvar);
      Rmod := modpx(RR, p, xvar);
      LL, RR := euclidcolumnreduce(LL, RR, Rmod, i0, j0, p, xvar, yvar);
      Rmod := modpx(RR, p, xvar);
    end do;
    i0 := i0 + 1;
    j0 := j0 + 1;
    r1 := checkzerorow(Rmod, i0);
  end do;
  D0 := LinearAlgebra:-RowOperation(D0, r1, p);

```

```

RR := Typesetting:-delayDotProduct(1/D0, RR);
return simplify(Typesetting:-delayDotProduct(LL, D0)), simplify(RR)
end proc
> preliminaryfactor := proc(M, xvar, yvar)

# Compute the primitive decomposition of the matrix M

local m, n, L, R, gg, pl, lpl, ii, p;
m := RowDimension(M);
n := ColumnDimension(M);
L := IdentityMatrix(m);
R := M;
gg := content(gcdvector(MaxMinors(M)), yvar);
pl := factorirrfactors(gg);
lpl := numelems(pl);
for ii from 1 to lpl do
    p := pl[ii];
    L, R := factorsingleirrfactor(L, R, p, xvar, yvar);
end do;
return L, R;
end proc;
preliminaryfactor := proc(M, xvar, yvar)
local m, n, L, R, gg, pl, lpl, ii, p;
m := LinearAlgebra:-RowDimension(M);
n := LinearAlgebra:-ColumnDimension(M);
L := LinearAlgebra:-IdentityMatrix(m);
R := M;
gg := content(gcdvector(MaxMinors(M)), yvar);
pl := factorirrfactors(gg);
lpl := numelems(pl);
for ii to lpl do
    p := pl[ii]; L, R := factorsingleirrfactor(L, R, p, xvar, yvar)
end do;
return L, R
end proc

```

(1.13)

## 2.new algo

```

> newsyzyalg := proc(M, svar, tvar)
# outputs the syzygy module generated by the column of the matrix M;
# M a matrix with entries of two variables;

```

```

# svar tvar variable
local V, Q, n, m, V2, L, R, W;
V2 := (Matrix(SyzygyModule( $M^{\%T}$ , [tvar]))); V2 := V2 $^{\%T}$ ;
m := RowDimension(M);
n := ColumnDimension(M);
W := simplify(V2 • diagdenomcol(V2));
L, R := preliminaryfactor( $W^{\%T}$ , svar, tvar);
return  $R^{\%T}$ ;
end proc;
newsyzalg := proc(M, svar, tvar)
    local V, Q, n, m, V2, L, R, W;
    V2 := Matrix(SyzygyModule( $M^{\%T}$ , [tvar]));
    V2 := V2 $^{\%T}$ ;
    m := LinearAlgebra:-RowDimension(M);
    n := LinearAlgebra:-ColumnDimension(M);
    W := simplify(Typesetting:-delayDotProduct(V2, diagdenomcol(V2)));
    L, R := preliminaryfactor( $W^{\%T}$ , svar, tvar);
    return  $R^{\%T}$ ;
end proc

```

(2.1)

### 3. previous algorithm by chen et al

```

> checknonzerominor := proc(M)

# Determine whether a matrix M has a non-zero minor
# Requires matrix rows to be smaller than columns and full rank

    local m, l, r, cc, k, i;
    l := RowDimension(M);
    m := ColumnDimension(M);
    r := m - l;
    cc := choose(m, l);
    k := numelems(cc);
    for i from 1 to k do
        if simplify(Determinant(SubMatrix(M, [1..l], cc[i]))) ≠ 0 then
            return cc[i];
        end if;
    end do;
end proc;
checknonzerominor := proc(M)
    local m, l, r, cc, k, i;
    l := LinearAlgebra:-RowDimension(M);
    m := LinearAlgebra:-ColumnDimension(M);

```

(3.1)

```

    r := m - l;
    cc := combinat:-choose(m, l);
    k := numelems(cc);
    for i to k do
        if simplify(LinearAlgebra:-Determinant(LinearAlgebra:-SubMatrix(M, [1
        .. l], cc[i]))) <> 0 then
            return cc[i]
        end if
    end do
end proc

```

```

> shiftmat := proc(M, li)
    local m, l, coli, F1, F2;
    l := RowDimension(M);
    m := ColumnDimension(M);
    coli := [op({`$`(1 .. m)} \ {op(li)})];
    F1 := SubMatrix(M, [1.. l], li);
    F2 := SubMatrix(M, [1.. l], coli);
    return F1, F2;
end proc;

```

```

shiftmat := proc(M, li)

```

(3.2)

```

    local m, l, coli, F1, F2;
    l := LinearAlgebra:-RowDimension(M);
    m := LinearAlgebra:-ColumnDimension(M);
    coli := [op({`$`(1..m)}minus{op(li)})];
    F1 := LinearAlgebra:-SubMatrix(M, [1.. l], li);
    F2 := LinearAlgebra:-SubMatrix(M, [1.. l], coli);
    return F1, F2

```

```

end proc

```

```

> step1 := proc(F1, F2)

```

# step1 in previous algorithm by chen et al

```

    local F22, A, B, i, r, ll, dd ;
    r := ColumnDimension(F2);
    F22 := -1·F2;
    A := simplify(Adjoint(F1) . F22);
    ll := [ ];
    dd := simplify(Determinant(F1));
    for i from 1 to r do
        ll := [op(ll), dd];
    end do;
    B := DiagonalMatrix(ll);
    return Matrix([[A], [B]]);

```

```

end proc;
step1 := proc(F1, F2)
    local F22, A, B, i, r, ll, dd;
    r := LinearAlgebra:-ColumnDimension(F2);
    F22 := - F2;
    A := simplify(Typesetting:-delayDotProduct(LinearAlgebra:-Adjoint(F1),
    F22));
    ll := [ ];
    dd := simplify(LinearAlgebra:-Determinant(F1));
    for i to r do ll := [op(ll), dd] end do;
    B := LinearAlgebra:-DiagonalMatrix(ll);
    return Matrix([A], [B]);
end proc

```

(3.3)

```

> oldsyzalg := proc(M, svar, tvar)
    local l, m, r, li, Hx, HH, F1, F2, G1, H1, E, HH1, V, H2, L, R, H3, V1, Ht;
    l := RowDimension(M);
    m := ColumnDimension(M);
    r := m - l;
    li := checknonzerominor(M);
    F1, F2 := shiftmat(M, li);
    Hx := step1(F1, F2);
    HH := Hx%T;
    G1, H1 := preliminaryfactor(HH, svar, tvar);
    HH1, E := HermiteFormcolumn(H1, tvar, output = [ 'H', 'U' ]);
    V := simplify(E • diagdenomcol(E));
    H2 := SubMatrix(simplify(H1 • V), [1..r], [1..r]);
    L, R := preliminaryfactor(H2%T, svar, tvar);
    H3 := L%T;
    V1 := simplify(SubMatrix(Adjoint(V), [1..r], [1..m]));
    Ht := simplify( $\left( \frac{1}{\text{Determinant}(V)} \right) \cdot (H3 \cdot V1)$ );
    return Ht%T;
end proc;

```

(3.4)

```

oldsyzalg := proc(M, svar, tvar)
    local l, m, r, li, Hx, HH, F1, F2, G1, H1, E, HH1, V, H2, L, R, H3, V1, Ht;
    l := LinearAlgebra:-RowDimension(M);
    m := LinearAlgebra:-ColumnDimension(M);
    r := m - l;
    li := checknonzerominor(M);
    F1, F2 := shiftmat(M, li);
    Hx := step1(F1, F2);
    HH := Hx^`%T`;

```

```

G1, H1 := preliminaryfactor(HH, svar, tvar);
HH1, E := MatrixPolynomialAlgebra:-HermiteForm[column](H1, tvar, output = [
' H' , ' U' ]);
V := simplify(Typesetting:-delayDotProduct(E, diagdenomcol(E)));
H2 := LinearAlgebra:-SubMatrix(simplify(Typesetting:-delayDotProduct(H1,
V)), [1..r], [1..r]);
L, R := preliminaryfactor(H2^`%T`, svar, tvar);
H3 := L^`%T`;
V1 := simplify(LinearAlgebra:-SubMatrix(LinearAlgebra:-Adjoint(V), [1
..r], [1..m]));
Ht := simplify(Typesetting:-delayDotProduct(H3, V1) / LinearAlgebra:-
Determinant(V));
return Ht^`%T`
end proc

```

#### 4.example

```

test1 := Matrix([[2·s·t, 2·t, 2·s, s2 + t2 + 1]]);
F := newsyvalg(test1, s, t);
simplify(test1·F);
gcdvector(MaxMinors(F));

```

$$test1 := \begin{bmatrix} 2 & s & t & 2 & t & 2 & s & s^2 + t^2 + 1 \end{bmatrix}$$

$$F := \begin{bmatrix} 1 & 0 & 0 \\ -s & s & t & -t^2 - 1 \\ 0 & s^2 + 1 & -s & t \\ 0 & -2 & s & 2 & t \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 0 \end{bmatrix}$$

1

(4.1)

```

st := time[real]():
F := newsyvalg(test1, s, t):
print("Computing Syzygy module using new algo costs:", time[real]() - st, "s");

st := time[real]():
F := oldsyvalg(test1, s, t):
print("Computing Syzygy module using previous algo costs:", time[real]() - st, "s");

```

```

st := time[real]():
F := BasisOfKernelModule(test1%T, [s, t], true):
print("Computing Syzygy module using QSAgorithm algo costs:", time[real]() - st,
"s");
"Computing Syzygy module using new algo costs:", 0.017, "s"
"Computing Syzygy module using previous algo costs:", 0.039, "s"
"Computing Syzygy module using QSAgorithm algo costs:", 0.088, "s" (4.2)

```

```

test2 := Matrix([[t^2 + s·t + 2·s^2 - 2·s^2·t, t^2 + 2·s·t + s·t^2 + 2·s^2 - s^2·t + 2·s^2·t^2, -t^2
+ s·t + 2·s·t^2 + 2·s^2 - s^2·t - 2·s^2·t^2, 2·s·t - 2·s·t^2 - 2·s^2·t - s^2·t^2]]);

```

```

F := newsyzyalg(test2, s, t);
simplify(test2·F);
gcdvector(MaxMinors(F));

```

```

test2 := [-2 s^2 t + 2 s^2 + s t + t^2, 2 s^2 t^2 - s^2 t + t^2 s + 2 s^2 + 2 s t + t^2,
-2 s^2 t^2 - s^2 t + 2 t^2 s + 2 s^2 + s t - t^2, -s^2 t^2 - 2 s^2 t - 2 t^2 s + 2 s t]

```

```

F := [[ (4936 s^2 - 5451 s + 695) (2797 s^2 + 388 s + 796), 13805992 s^4
- 12224839 s^3 + 2236628 s^2 - 3516116 s, 10339020934466 s^4
- 17294200417877 s^3 + 78976 s^2 t + 182436801594859 s^2 - 29072 s t
- 15899956275703 s + 11120 t + 1554400694933 ],
[ - 8628745 s^4 + 6822019 s^3 - 6648983 s^2 + 525117 s - 138305, - 1725749 s^4
+ 6130494 s^3 - 12468136 s^2 + 5194964 s, - 25847552336165 s^4
+ 181322742315229 s^3 - 49360 s^2 t - 196186886482601 s^2 + 45872 s t
+ 29232213501799 s - 63584 t - 1554400694933 ],
[
- 1/209856 ((5177247 s^3 - 6509260 s^2 - 1678848 s t - 9539983 s - 3357696 t
+ 2232068) s),
- 1/138305 (s (5177247 s^3 - 6094345 s^2 - 1678848 s t - 10231508 s

```

$$\begin{aligned}
& -3357696 \ t + 1678848) \Big), \ -\frac{5169510467233 \ s^4}{556548740332} + \frac{355330194783917 \ s^3}{6678584883984} \\
& + \frac{(-40205054422272 \ t - 154936631819375) \ s^2}{6678584883984} \\
& + \frac{(20323137211904 \ t - 637973298940364) \ s}{6678584883984} - 16 \ t \Big], \\
& \left[ -\frac{1725749}{52464} \ s^4 - \frac{1517243}{69952} \ s^3 - 16 \ s^2 \ t - \frac{1340863}{209856} \ s^2 + 16 \ s \ t - \frac{1298741}{104928} \ s - 8 \ t \right. \\
& + \frac{138305}{104928}, \ -\frac{6902996 \ s^4}{138305} - \frac{5104949 \ s^3}{138305} + \frac{(-3357696 \ t - 1479168) \ s^2}{138305} \\
& + \frac{(3357696 \ t - 2597482) \ s}{138305} - \frac{1678848 \ t}{138305}, \ -\frac{5169510467233 \ s^4}{417411555249} \\
& + \frac{3031172487661 \ s^3}{64217162346} + \frac{(-120660308888576 \ t + 333686920694963) \ s^2}{6678584883984} \\
& + \frac{(206590901700864 \ t + 105414662675448) \ s}{6678584883984} - \frac{12801708880 \ t}{381895293} + \frac{1554400694933}{85622883128} \\
& \left. \right]
\end{aligned}$$

$$\begin{bmatrix} 0 & 0 & 0 \end{bmatrix}$$

512

(4.3)

```

st := time[real]():
F := newsyzyalg(test2, s, t):
print("Computing Syzygy module using new algo costs:", time[real]() - st, "s");

st := time[real]():
F := oldsyzyalg(test2, s, t):
print("Computing Syzygy module using previous algo costs:", time[real]() - st, "s");

```

```

st := time[real]():
F := BasisOfKernelModule(test2%T, [s, t], true):
print("Computing Syzygy module using QSAalgorithm algo costs:", time[real]() - st,
"s");

```

"Computing Syzygy module using new algo costs:", 0.117, "s"

"Computing Syzygy module using previous algo costs:", 0.114, "s"

"Computing Syzygy module using QSAalgorithm algo costs:", 0.483, "s"

(4.4)



```

test3 := Matrix([[-3*s^2*t^2 + 5*s^2*t - 5*t^2 - 4*s*t + 5, -3*s^2*t^2 + 3*s^2*t + s^2 + s*t^2 - s
- 2*t^2 - 5*s*t + 1, -5*s^2*t^2 + 6*s^2*t + 2*s*t - t^2 - t - 5, -4*s^2*t^2 + 3*s^2*t - s*t + 6*t^2
- t + 1]]);
F := newsyralg(test3, s, t);
simplify(test3•F);
gcdvector(MaxMinors(F));
test3 := [-3 s^2 t^2 + 5 s^2 t - 4 s t - 5 t^2 + 5, -3 s^2 t^2 + 3 s^2 t + t^2 s + s^2
- 5 s t - 2 t^2 - s + 1, -5 s^2 t^2 + 6 s^2 t + 2 s t - t^2 - t - 5, -4 s^2 t^2
+ 3 s^2 t - s t + 6 t^2 - t + 1]

[ 0 0 0 ]
2916 (4.5)

```

```

st := time[real]();
F := newsyralg(test3, s, t);
print("Computing Syzygy module using new algo costs:", time[real]() - st, "s");

st := time[real]();
F := oldsyralg(test3, s, t);
print("Computing Syzygy module using previous algo costs:", time[real]() - st, "s");

"Computing Syzygy module using new algo costs:", 0.089, "s"
"Computing Syzygy module using previous algo costs:", 0.105, "s" (4.6)

```

```

test4 := [[-s t - s + 2 t, 3 s^2 + 3 s t - 3 t, s^2 - 2 t - 3, -s^2 + 2 t^2, 2 + 3 s, 3 s t - t
+ 2, -3 s^2 - s + 1, -3 t^2 - 2 s - 3 t],
[-3 t^2 + 3 s - 1, s^2 + s t - 3 t^2, 2 s t + t^2 + 2 s, -s^2 + 2 t^2 - 2, 2 + 2 s - t, s t
+ 2 t^2 + 3 t, -3 t^2 - 3 t, -2 s^2 - 2 s t - 3],
[s^2 - 2 t^2 - t, 2 s^2 + 3 s t - 3 s, -3 t^2 - 2, 1 + 3 s + 3 t, -2 s t + 3 t^2 + t, -3 s t
- 2 t + 3, -t^2 - 2 t, s t - t]];
F := newsyralg(test4, s, t);
simplify(test4•F);
#gcdvector(MaxMinors(F));
test4 := [[-s t - s + 2 t, 3 s^2 + 3 s t - 3 t, s^2 - 2 t - 3, -s^2 + 2 t^2, 2
+ 3 s, 3 s t - t + 2, -3 s^2 - s + 1, -3 t^2 - 2 s - 3 t],
[-3 t^2 + 3 s - 1, s^2 + s t - 3 t^2, 2 s t + t^2 + 2 s, -s^2 + 2 t^2 - 2, 2 + 2 s
- t, s t + 2 t^2 + 3 t, -3 t^2 - 3 t, -2 s^2 - 2 s t - 3],
[s^2 - 2 t^2 - t, 2 s^2 + 3 s t - 3 s, -3 t^2 - 2, 1 + 3 s + 3 t, -2 s t + 3 t^2
+ t, -3 s t - 2 t + 3, -t^2 - 2 t, s t - t]]

```

$$\begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad (4.7)$$

```

st := time[real]():
F := newsyralg(test4, s, t):
print("Computing Syzygy module using new algo costs:", time[real]() - st, "s");

st := time[real]():
F := oldsyralg(test4, s, t):
print("Computing Syzygy module using previous algo costs:", time[real]() - st, "s");

```

```

"Computing Syzygy module using new algo costs:", 3.059, "s"
"Computing Syzygy module using previous algo costs:", 34.374, "s"

```

(4.8)

```

test5 := [[3 s + t + 2, 2 t + 1, 2 s - 3, 3 s + t + 3, 3 s - t + 1, -3 s - 1, -s - 1, -s
+ t - 2, -s - 2 t - 1, -2 t + 1],
[-2 s - 2 t - 3, 2 s + 2 t - 3, 2 s + 1, -s + t + 2, -3 s - 2, s - 2 t - 3, 3 t - 3,
-2 s + 3 t + 3, s + 3 t - 3, -2 s],
[-s + 3 t + 3, -s - 3, -s + 3 t - 1, -3 s - t + 2, 3 t + 1, 2 s - t + 1, 3 s + 3 t
- 2, -2 s + 1, 2 s + 3 t - 1, t - 3],
[t + 1, s - 2 t, -2 s + 2 t + 1, 3 s - 3 t, s + 2 t + 2, -s + t + 1, 3 s - 2 t + 2,
-3 s - t + 1, s + 3 t - 2, 2 s - 2],
[s + t - 3, 2 s, 3 s + t + 2, -2 s - t - 1, -s - 2, -s - t - 1, 2 s - t + 1, 2 s - t
- 3, s + 2, 2 s + 3],
[-s - 1, -s + 3 t - 2, 3 s + 3 t + 1, -2 s + 2 t, -3 s + 3 t + 3, 2 s - 2 t - 2, -3 s
+ 2, -3 s + 3 t - 2, 2 s - t + 2, 3 s - 2 t]];
F := newsyralg(test5, s, t):
simplify(test5 • F);
#gcdvector(MaxMinors(F));
test5 := [[3 s + t + 2, 2 t + 1, 2 s - 3, 3 s + t + 3, 3 s - t + 1, -3 s - 1,
-s - 1, -s + t - 2, -s - 2 t - 1, -2 t + 1],
[-2 s - 2 t - 3, 2 s + 2 t - 3, 2 s + 1, -s + t + 2, -3 s - 2, s - 2 t
- 3, 3 t - 3, -2 s + 3 t + 3, s + 3 t - 3, -2 s],
[-s + 3 t + 3, -s - 3, -s + 3 t - 1, -3 s - t + 2, 3 t + 1, 2 s - t + 1,
3 s + 3 t - 2, -2 s + 1, 2 s + 3 t - 1, t - 3],
[t + 1, s - 2 t, -2 s + 2 t + 1, 3 s - 3 t, s + 2 t + 2, -s + t + 1, 3 s
- 2 t + 2, -3 s - t + 1, s + 3 t - 2, 2 s - 2],
[s + t - 3, 2 s, 3 s + t + 2, -2 s - t - 1, -s - 2, -s - t - 1, 2 s - t
+ 1, 2 s - t - 3, s + 2, 2 s + 3],
[-s - 1, -s + 3 t - 2, 1 + 3 s + 3 t, -2 s + 2 t, -3 s + 3 t + 3, 2 s - 2 t
- 2, -3 s + 2, -3 s + 3 t - 2, 2 + 2 s - t, 3 s - 2 t]]

```

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad (4.9)$$

```

st := time[real]() :
F := newsyalg(test5, s, t) :
print("Computing Syzygy module using new algo costs:", time[real]() - st, "s");

st := time[real]() :
F := oldsyalg(test5, s, t) :
print("Computing Syzygy module using previous algo costs:", time[real]() - st, "s");

"Computing Syzygy module using new algo costs:", 2.079, "s"
"Computing Syzygy module using previous algo costs:", 56.329, "s"

```

**(4.10)**